Optimal surface salinity perturbations of the Meridional Overturning Circulation

#### Florian Sévellec (Yale Univ.), Thierry Huck (CNRS), Jérôme Vialard (IRD) and Alexey Fedorov (Yale Univ.)

Department of Geology and Geophysics, Yale University



EGU April 2009



## Climate context (1) : The MOC

- Slow dynamics of the ocean :
- Meridional Overturning Circulation (MOC)
  - Intensity of  ${\sim}18~{\rm Sv}$
  - Time scale of  ${\sim}500$  ans



・ロン ・回 と ・ ヨン ・ ヨン

Northward transport of heat influencing the European climate ⇒ Variability of the meridional overturning circulation

## Climate context (1) : The MOC

- Slow dynamics of the ocean :
- Meridional Overturning Circulation (MOC)
  - $\bullet~$  Intensity of  ${\sim}18~\text{Sv}$
  - Time scale of  ${\sim}500$  ans



・ロン ・回 と ・ヨン ・ヨン

Northward transport of heat influencing the European climate ⇒ Variability of the meridional overturning circulation

# Climate context (1) : The MOC

- Slow dynamics of the ocean :
- Meridional Overturning Circulation (MOC)
  - $\bullet$  Intensity of  ${\sim}18~\text{Sv}$
  - Time scale of  ${\sim}500$  ans



・ロト ・ 同ト ・ ヨト ・ ヨト

Northward transport of heat influencing the European climate

 $\Rightarrow$  Variability of the meridional overturning circulation

### Climate context (2) : North Atl. P-E

- Increase of precipitation in the north Atlantic
  - $\rightarrow$  Josey and Marsh (2005)



(a)

What is the impact of the SSS modification on the meridional overturning circulation?

### Climate context (2) : North Atl. P-E

- Increase of precipitation in the north Atlantic
  - $\rightarrow$  NCEP reanalysys



・ロト ・回ト ・ヨト ・ヨト

What is the impact of the SSS modification on the meridional overturning circulation?

### Climate context (2) : North Atl. P-E

- Increase of precipitation in the north Atlantic
  - $\rightarrow$  NCEP reanalysys



・ロト ・同ト ・ヨト ・ヨト

# What is the impact of the SSS modification on the meridional overturning circulation?

### Approach

#### $\Rightarrow$ Forced variability of the ocean circulation

- Linear approach : weak variations (perturbations) of the ocean circulation
- Generalized stability analysis :
  - Atmosphere ⇒ optimal initial and stochastic perturbation (Farrell and Ioannou, 1996)
  - Ocean ⇒ optimal initial perturbation (Moore and Farrell, 1993)
  - 3 box THC ⇒ optimal initial and stochastic perturbation (Tziperman and Ioannou, 2002)

・ロン ・四 ・ ・ ヨ ・ ・ ヨ ・ ・

### Approach

#### $\Rightarrow$ Forced variability of the ocean circulation

- Linear approach : weak variations (perturbations) of the ocean circulation
- Generalized stability analysis :
  - Atmosphere  $\Rightarrow$  optimal initial and stochastic perturbation (Farrell and Ioannou, 1996)
  - Ocean  $\Rightarrow$  optimal initial perturbation (Moore and Farrell, 1993)
  - 3 box THC  $\Rightarrow$  optimal initial and stochastic perturbation (Tziperman and Ioannou, 2002)

(日) (종) (종) (종) (종)

#### Maximization method : Oceanic circulation application

#### Goal :

• Optimal impact of the SSS on the circulation

#### Lagrange parameters method

- Functions to maximize  $\langle F|u(t)\rangle$  (or  $\langle F|u(t)\rangle^2$ ) :
  - Meridional Overturning Circulation (MOC) at the latitude and depth of its steady state maximum (or its variance)
- Constraints
  - 1 Normalisation :  $\langle u(0)|\mathbf{S}|u(0)\rangle = 1$
  - 2 Salt conservation :  $\langle C|u(0)\rangle = 0$
  - **(3)** Only surface salinity perturbation :  $|u(0)
    angle = {\sf P} |u'
    angle$

・ロン ・四 ・ ・ ヨ ・ ・ ヨ ・ ・

#### Maximization method : Oceanic circulation application

#### Goal :

• Optimal impact of the SSS on the circulation

#### Lagrange parameters method

- Functions to maximize  $\langle F|u(t)\rangle$  (or  $\langle F|u(t)\rangle^2$ ) :
  - Meridional Overturning Circulation (MOC) at the latitude and depth of its steady state maximum (or its variance)
- Constraints
  - 1 Normalisation :  $\langle u(0)|\mathbf{S}|u(0)\rangle = 1$
  - 2 Salt conservation :  $\langle C|u(0)\rangle = 0$
  - **(3)** Only surface salinity perturbation :  $|u(0)\rangle = \mathbf{P} |u'\rangle$

(日) (종) (종) (종) (종)

#### Maximization method : Oceanic circulation application

#### $\mathsf{Goal} \,:\,$

• Optimal impact of the SSS on the circulation

#### Lagrange parameters method

- Functions to maximize  $\langle F|u(t)\rangle$  (or  $\langle F|u(t)\rangle^2$ ) :
  - Meridional Overturning Circulation (MOC) at the latitude and depth of its steady state maximum (or its variance)
- Constraints
  - **1** Normalisation :  $\langle u(0)|\mathbf{S}|u(0)\rangle = 1$
  - 2 Salt conservation :  $\langle C|u(0)\rangle = 0$
  - 3 Only surface salinity perturbation :  $|u(0)\rangle = \mathbf{P} |u'\rangle$

### Optimal perturbation experiments

	2D	PG	OPA - ORCA2
Initial perturbation	Х	Х	X
Constant perturbation	Х		
Stochastic perturbation	Х	Х	

Latitude-depth model

 $\Rightarrow$  Methodological study Sévellec et al. (*J. Phys. Oceanogr.*, 2007)

- Planetary geostrophic model :
   ⇒ Influence of the surface boundary condition (flux vs mixed) Sévellec et al. (J. Phys. Oceanogr., in press)
- Ocean General Circulation Model Sévellec et al. (J. Phys. Oceanogr., 2008)

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

### Optimal perturbation experiments

	2D	PG	OPA - ORCA2
Initial perturbation	Х	Х	X
Constant perturbation	Х		
Stochastic perturbation	Х	Х	

#### • Latitude-depth model

 $\Rightarrow$  Methodological study Sévellec et al. (*J. Phys. Oceanogr.*, 2007)

- Planetary geostrophic model :
   ⇒ Influence of the surface boundary condition (flux vs mixed) Sévellec et al. (J. Phys. Oceanogr., in press)
- Ocean General Circulation Model Sévellec et al. (J. Phys. Oceanogr., 2008)

・ロン ・四 ・ ・ ヨ ・ ・ ヨ ・ ・

Approach Application in an Ocean General Circulation Model

### Optimal perturbation experiments

	2D	PG	OPA - ORCA2
Initial perturbation	Х	Х	Х
Constant perturbation	Х		
Stochastic perturbation	Х	Х	

• Latitude-depth model

 $\Rightarrow$  Methodological study Sévellec et al. (*J. Phys. Oceanogr.*, 2007)

• Planetary geostrophic model :

 $\Rightarrow$  Influence of the surface boundary condition (flux vs mixed) Sévellec et al. (*J. Phys. Oceanogr.*, in press)

 Ocean General Circulation Model Sévellec et al. (J. Phys. Oceanogr., 2008)

#### Optimal perturbation experiments

	2D	PG	OPA - ORCA2
Initial perturbation	Х	Х	Х
Constant perturbation	Х		
Stochastic perturbation	Х	Х	

• Latitude-depth model

 $\Rightarrow$  Methodological study Sévellec et al. (*J. Phys. Oceanogr.*, 2007)

- Planetary geostrophic model :
   ⇒ Influence of the surface boundary condition (flux vs mixed) Sévellec et al. (J. Phys. Oceanogr., in press)
- Ocean General Circulation Model Sévellec et al. (*J. Phys. Oceanogr.*, 2008)

### Upper bound in the 2D model

#### • Initial SSS perturbation :

Great Salinity Anomalies (GSA, Belkin et al., 1998) 0.5 psu on 250 m  $\Rightarrow$  2 Sv

#### Constant FW perturbation :

hydrological cycle modification in the global warming scenario (Held and Soden, 2006) 4% (3 cm yr<sup>-1</sup>)  $\Rightarrow$  0.14 Sv

#### • Stochastic FW perturbation :

Using 2 different reanalysis datasets 5 cm yr^{-1}  $\Rightarrow$  4.6 Sv

・ロン ・四 ・ ・ ヨ ・ ・ ヨ ・ ・

### Upper bound in the 2D model

#### • Initial SSS perturbation :

Great Salinity Anomalies (GSA, Belkin et al., 1998) 0.5 psu on 250 m  $\Rightarrow$  2 Sv

#### • Constant FW perturbation :

hydrological cycle modification in the global warming scenario (Held and Soden, 2006) 4% (3 cm yr<sup>-1</sup>)  $\Rightarrow 0.14$  Sv

#### • Stochastic FW perturbation :

Using 2 different reanalysis datasets 5 cm yr^{-1}  $\Rightarrow$  4.6 Sv

(日) (종) (종) (종) (종)

### Upper bound in the 2D model

#### • Initial SSS perturbation :

Great Salinity Anomalies (GSA, Belkin et al., 1998) 0.5 psu on 250 m  $\Rightarrow$  2 Sv

#### • Constant FW perturbation :

hydrological cycle modification in the global warming scenario (Held and Soden, 2006) 4% (3 cm yr<sup>-1</sup>)  $\Rightarrow$  0.14 Sv

#### • Stochastic FW perturbation :

Using 2 different reanalysis datasets 5 cm yr^{-1}  $\Rightarrow$  4.6 Sv

(日) (종) (종) (종) (종)

Approach Application in an Ocean General Circulation Model

### Results in the PG model

#### • Variability :

• Large scale gradient SSS efficiently stimulates a North Atl. multidecadal oscillation.

#### • Surface boundary condition :

- The sensitivity pattern weakly depends of the surface boundary condition.
- The intensity of the response strongly depends of the boundary condition.

Approach Application in an Ocean General Circulation Model

### Results in the PG model

- Variability :
  - Large scale gradient SSS efficiently stimulates a North Atl. multidecadal oscillation.
- Surface boundary condition :
  - The sensitivity pattern weakly depends of the surface boundary condition.
  - The intensity of the response strongly depends of the boundary condition.

### Results in the PG model

- Variability :
  - Large scale gradient SSS efficiently stimulates a North Atl. multidecadal oscillation.
- Surface boundary condition :
  - The sensitivity pattern weakly depends of the surface boundary condition.
  - The intensity of the response strongly depends of the boundary condition.

Approach Application in an Ocean General Circulation Model

#### Application in an Ocean General Circulation Model

#### Model : OPA 8.2, ORCA2, OPATAM





• MAX(MOC)=7 Sv (48°N)



• MAX(MHT)=0.6 PW (27°N)

Florian Sévellec

Optimal surface salinity perturbations of the MOC

Approach Application in an Ocean General Circulation Model

#### Optimal initial SSS perturbation for the MOC



Maximum growth after 10.5 yr

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

Э

#### Approach Application in an Ocean General Circulation Model

Conclusions



Florian Sévellec

Optimal surface salinity perturbations of the MOC

Approach Application in an Ocean General Circulation Model

#### Finite time growth mechanism



 $\alpha \partial_{\phi} \bar{T} \gg \beta \partial_{\phi} \bar{S}$ 



・ロン ・回 と ・ ヨン ・ ヨン

Э

Florian Sévellec Optimal surface salinity perturbations of the MOC

Approach Application in an Ocean General Circulation Model

#### Finite time growth mechanism



 $\alpha \partial_{\phi} \bar{T} \gg \beta \partial_{\phi} \bar{S}$ 

 $\mathrm{SSS}'_{\mathrm{north}} > 0 \Rightarrow \nu'_{\mathrm{surf}} > 0$ 

Approach Application in an Ocean General Circulation Model

#### Finite time growth mechanism



 $\alpha \partial_{\phi} \bar{T} \gg \beta \partial_{\phi} \bar{S}$ 

 $\mathrm{SSS}'_\mathrm{north} > 0 \Rightarrow v'_\mathrm{surf} > 0$ 

Approach Application in an Ocean General Circulation Model

#### Finite time growth mechanism



 $\alpha \partial_{\phi} \bar{T} \gg \beta \partial_{\phi} \bar{S}$ 

 $SSS'_{north} > 0 \Rightarrow v'_{surf} > 0$ 

Approach Application in an Ocean General Circulation Model

#### Finite time growth mechanism



・ロン ・四 ・ ・ ヨ ・ ・ ヨ ・ ・

Э

Approach Application in an Ocean General Circulation Model

#### Nonlinear - linear comparison



• Relative error : less than 20%

• Max bound :  $GSA \Rightarrow 0.75 \text{ Sv}$  $(11\% \text{ of } \overline{\text{MOC}})$ 

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

Э

Approach Application in an Ocean General Circulation Model

#### Nonlinear - linear comparison



• Relative error : less than 20%

• Max bound :  $GSA \Rightarrow 0.75 \text{ Sv}$  $(11\% \text{ of } \overline{\text{MOC}})$ 

( ) < </p>

臣

Florian Sévellec Optimal surface salinity perturbations of the MOC

- Efficient method to obtain the optimal initial perturbation :
   ⇒ Explicit solution (adj. model)
- Results of the 2D, PG and OGCM models
   Similarity :
  - to 30, the sensitivity is dominated by the Salinity
  - $\Rightarrow$  Difference : Transient growth mechanism
- Optimal SSS perturbation of the MOC in an OGCM
- Upper bound of the impact of SSS on MOC

- Efficient method to obtain the optimal initial perturbation :
   ⇒ Explicit solution (adj. model)
- Results of the 2D, PG and OGCM models  $\Rightarrow$  Similarity :
  - Optimal pert. are large scale North-South gradient
  - In 3D, the sensitivity is dominated by the Salinity and the response is dominated by the Temperature
  - $\Rightarrow$  Difference : Transient growth mechanism
- Optimal SSS perturbation of the MOC in an OGCM
- Upper bound of the impact of SSS on MOC

・ロン ・回 と ・ ヨン ・ ヨン

- Efficient method to obtain the optimal initial perturbation :
   ⇒ Explicit solution (adj. model)
- Results of the 2D, PG and OGCM models
   ⇒ Similarity :
  - Optimal pert. are large scale North-South gradient
  - In 3D, the sensitivity is dominated by the Salinity and the response is dominated by the Temperature
  - $\Rightarrow$  Difference : Transient growth mechanism
- Optimal SSS perturbation of the MOC in an OGCM
   Growth mechanism
- Upper bound of the impact of SSS on MOC

・ロン ・回 と ・ ヨン ・ ヨン

- Efficient method to obtain the optimal initial perturbation :
   ⇒ Explicit solution (adj. model)
- Results of the 2D, PG and OGCM models
   ⇒ Similarity :
  - Optimal pert. are large scale North-South gradient
  - In 3D, the sensitivity is dominated by the Salinity and the response is dominated by the Temperature
  - $\Rightarrow$  **Difference** : Transient growth mechanism
- Optimal SSS perturbation of the MOC in an OGCM
   Growth mechanism
- Upper bound of the impact of SSS on MOC

- Efficient method to obtain the optimal initial perturbation :
   ⇒ Explicit solution (adj. model)
- Results of the 2D, PG and OGCM models
   ⇒ Similarity :
  - Optimal pert. are large scale North-South gradient
  - In 3D, the sensitivity is dominated by the Salinity and the response is dominated by the Temperature
  - $\Rightarrow$  Difference : Transient growth mechanism
- Optimal SSS perturbation of the MOC in an OGCM
   ⇒ Growth mechanism
- Upper bound of the impact of SSS on MOC

・ロン ・回 と ・ヨン ・ ヨン

- Efficient method to obtain the optimal initial perturbation :
   ⇒ Explicit solution (adj. model)
- Results of the 2D, PG and OGCM models  $\Rightarrow$  Similarity :
  - Optimal pert. are large scale North-South gradient
  - In 3D, the sensitivity is dominated by the Salinity and the response is dominated by the Temperature
  - $\Rightarrow$  Difference : Transient growth mechanism
- Optimal SSS perturbation of the MOC in an OGCM  $\Rightarrow$  Growth mechanism
- Upper bound of the impact of SSS on MOC

イロト イポト イヨト イヨト

### Future work

#### • Optimal wind stress perturbation

- Impact of the Southern Ocean
- Mechanism of the finite time growth
- Seasonal cycle (non-autonomous operator)
   Sensitivity to the season



#### • Tropical study :

 Optimal ocean perturbation and phase locking of ENSO (ENSEMBLES, European project for climate changes prediction)

( ) < </p>

### Future work

- Optimal wind stress perturbation
  - Impact of the Southern Ocean
  - Mechanism of the finite time growth
- Seasonal cycle (non-autonomous operator)
  - Sensitivity to the season

### • Tropical study



 Optimal ocean perturbation and phase locking of ENSO (ENSEMBLES, European project for climate changes prediction)

・ロト ・同ト ・ヨト ・ヨト

### Future work

- Optimal wind stress perturbation
  - Impact of the Southern Ocean
  - Mechanism of the finite time growth
- Seasonal cycle (non-autonomous operator)
  - Sensitivity to the season

#### • Tropical study :

• Optimal ocean perturbation and phase locking of ENSO (ENSEMBLES, European project for climate changes prediction)



・ロト ・ 同ト ・ ヨト ・ ヨト

### Future work

- Optimal wind stress perturbation
  - Impact of the Southern Ocean
  - Mechanism of the finite time growth
- Seasonal cycle (non-autonomous operator)
  - Sensitivity to the season
- Tropical study :

• Optimal ocean perturbation and phase locking of ENSO (ENSEMBLES, European project for climate changes prediction)

#### Thank you for your attention



・ロト ・ 同ト ・ ヨト ・ ヨト

Results Future work

▲□> < @> < E> < E> < E</li>

Results Future work

#### Optimal initial SSS perturbation

Perturbation evolution (autonomous problem) :

 $\partial_t \left| u \right\rangle = \mathbf{A} \left| u \right\rangle,$ 

$$\Rightarrow |u(\tau)\rangle = \mathsf{M}(\tau) |u(0)\rangle = e^{\mathbf{A}_{\tau}} |u(0)\rangle.$$

Explicit solution (using the adjoint model) of the optimal initial perturbation :

$$\Rightarrow |u(0)\rangle = \mathbf{P} |u'\rangle$$
$$|u'\rangle = (2\gamma_1)^{-1} \left( \mathbf{N}^{-1} \mathbf{P}^{\dagger} \mathbf{M}^{\dagger}(\tau) |F\rangle - \gamma_2 \mathbf{N}^{-1} \mathbf{P}^{\dagger} |C\rangle \right), \text{ with } \mathbf{N} = \mathbf{P}^{\dagger} \mathbf{S} \mathbf{P},$$
$$\gamma_1 = \operatorname{fct} \left( \mathbf{M}^{\dagger}(\tau) |F\rangle, |C\rangle, \mathbf{N}, \mathbf{P}, \gamma_2 \right) \text{ and}$$
$$\gamma_2 = \operatorname{fct} \left( \mathbf{M}^{\dagger}(\tau) |F\rangle, |C\rangle, \mathbf{N}, \mathbf{P} \right).$$

Results Future work

### Optimal initial SSS perturbation

Perturbation evolution (autonomous problem) :

 $\partial_t \left| u \right\rangle = \mathbf{A} \left| u \right\rangle,$ 

$$\Rightarrow |u(\tau)\rangle = \mathbf{M}(\tau) |u(0)\rangle = e^{\mathbf{A}_{\tau}} |u(0)\rangle.$$

**Explicit solution** (using the adjoint model) of the optimal initial perturbation :

$$\Rightarrow |u(0)\rangle = \mathbf{P} |u'\rangle$$
$$|u'\rangle = (2\gamma_1)^{-1} \left( \mathbf{N}^{-1} \mathbf{P}^{\dagger} \mathbf{M}^{\dagger}(\tau) |F\rangle - \gamma_2 \mathbf{N}^{-1} \mathbf{P}^{\dagger} |C\rangle \right), \text{ with } \mathbf{N} = \mathbf{P}^{\dagger} \mathbf{S} \mathbf{P},$$
$$\gamma_1 = \operatorname{fct} \left( \mathbf{M}^{\dagger}(\tau) |F\rangle, |C\rangle, \mathbf{N}, \mathbf{P}, \gamma_2 \right) \text{ and}$$
$$\gamma_2 = \operatorname{fct} \left( \mathbf{M}^{\dagger}(\tau) |F\rangle, |C\rangle, \mathbf{N}, \mathbf{P} \right).$$

Results Future work

### Optimal initial SSS perturbation

Perturbation evolution (autonomous problem) :

 $\partial_t \left| u \right\rangle = \mathbf{A} \left| u \right\rangle,$ 

$$\Rightarrow |u(\tau)\rangle = \mathbf{M}(\tau) |u(0)\rangle = e^{\mathbf{A}_{\tau}} |u(0)\rangle.$$

Explicit solution (using the adjoint model) of the optimal initial perturbation :

$$\Rightarrow |u(0)\rangle = \mathbf{P} |u'\rangle$$
$$|u'\rangle = (2\gamma_1)^{-1} \left( \mathbf{N}^{-1} \mathbf{P}^{\dagger} \mathbf{M}^{\dagger}(\tau) |F\rangle - \gamma_2 \mathbf{N}^{-1} \mathbf{P}^{\dagger} |C\rangle \right), \text{ with } \mathbf{N} = \mathbf{P}^{\dagger} \mathbf{S} \mathbf{P},$$
$$\gamma_1 = \operatorname{fct} \left( \mathbf{M}^{\dagger}(\tau) |F\rangle, |C\rangle, \mathbf{N}, \mathbf{P}, \gamma_2 \right) \text{ and}$$
$$\gamma_2 = \operatorname{fct} \left( \mathbf{M}^{\dagger}(\tau) |F\rangle, |C\rangle, \mathbf{N}, \mathbf{P} \right).$$

 $\Rightarrow$  Solution depends on the maximization delay  $\tau$ 

### Efficient method :

Maximization under constraints :  $dG(\gamma, |u_0\rangle) = 0$ 

• Measure : Linear function

$$G(\gamma, |u_0\rangle) = \langle F|\mathbf{M}(\tau)|u_0
angle - \gamma(\langle u_0|\mathbf{S}|u_0
angle - 1)$$

Explicit soluton :

$$|u_0
angle = \pm rac{\mathbf{S}^{-1}\mathbf{M}^{\dagger}( au)|F
angle}{\sqrt{\langle F|\mathbf{M}( au)\mathbf{S}^{-1}\mathbf{M}^{\dagger}( au)|F
angle}}$$

Measure : quadratic norm

 $G(\gamma, |u_0\rangle) = \langle u_0 | \mathbf{M}^{\dagger}(\tau) | \mathbf{S}_2 | \mathbf{M}(\tau) | u_0 \rangle - \gamma(\langle u_0 | \mathbf{S}_1 | u_0 \rangle - 1)$ 

### Efficient method :

Maximization under constraints :  $dG(\gamma, |u_0\rangle) = 0$ 

• Measure : Linear function

$$G(\gamma, |u_0\rangle) = \langle F|\mathbf{M}(\tau)|u_0
angle - \gamma(\langle u_0|\mathbf{S}|u_0
angle - 1)$$

Explicit soluton :

$$|u_0
angle = \pm rac{\mathbf{S}^{-1}\mathbf{M}^{\dagger}(\tau)|F
angle}{\sqrt{\langle F|\mathbf{M}(\tau)\mathbf{S}^{-1}\mathbf{M}^{\dagger}(\tau)|F
angle}}$$

Measure : quadratic norm

 $G(\gamma, |u_0\rangle) = \langle u_0 | \mathbf{M}^{\dagger}(\tau) | \mathbf{S}_2 | \mathbf{M}(\tau) | u_0 \rangle - \gamma(\langle u_0 | \mathbf{S}_1 | u_0 \rangle - 1)$ 

 $\langle \gamma \mathbf{S_1} | u_0 
angle = \mathbf{M}^{\dagger}( au) \mathbf{S}_2 \mathbf{M}( au) | u_0 
angle, \langle u_0 | \mathbf{S}_1 | u_0 
angle = 1$ 

### Efficient method :

Maximization under constraints :  $dG(\gamma, |u_0\rangle) = 0$ 

• Measure : Linear function

$$G(\gamma, |u_0\rangle) = \langle F | \mathbf{M}(\tau) | u_0 
angle - \gamma(\langle u_0 | \mathbf{S} | u_0 
angle - 1)$$

Explicit soluton :

$$|u_0
angle = \pm rac{{f S}^{-1}{f M}^\dagger( au) |F
angle}{\sqrt{\langle F|{f M}( au){f S}^{-1}{f M}^\dagger( au)|F
angle}}$$

• Measure : quadratic norm

$$G(\gamma, |u_0
angle) = \langle u_0 | \mathbf{M}^{\dagger}( au) | \mathbf{S}_2 | \mathbf{M}( au) | u_0 
angle - \gamma(\langle u_0 | \mathbf{S}_1 | u_0 
angle - 1)$$

Eigenvalue solution :

 $\gamma \mathbf{S_1} \ket{u_0} = \mathbf{M}^{\dagger}( au) \mathbf{S_2} \mathbf{M}( au) \ket{u_0}, \, \langle u_0 | \mathbf{S_1} | u_0 
angle = 1$ 

### Efficient method :

Maximization under constraints :  $dG(\gamma, |u_0\rangle) = 0$ 

• Measure : Linear function

$$G(\gamma, |u_0\rangle) = \langle F | \mathbf{M}(\tau) | u_0 
angle - \gamma(\langle u_0 | \mathbf{S} | u_0 
angle - 1)$$

Explicit soluton :

$$|u_0
angle = \pm rac{{f S}^{-1}{f M}^\dagger( au) |F
angle}{\sqrt{\langle F|{f M}( au){f S}^{-1}{f M}^\dagger( au)|F
angle}}$$

• Measure : quadratic norm

$$G(\gamma, |u_0\rangle) = \langle u_0 | \mathbf{M}^{\dagger}( au) | \mathbf{S}_2 | \mathbf{M}( au) | u_0 
angle - \gamma(\langle u_0 | \mathbf{S}_1 | u_0 
angle - 1)$$

Eigenvalue solution :

$$\gamma \mathbf{S_1} \ket{u_0} = \mathbf{M}^{\dagger}( au) \mathbf{S_2} \mathbf{M}( au) \ket{u_0}, \, \langle u_0 | \mathbf{S_1} | u_0 
angle = 1$$